

An Improved Estimation Method for Single Image Dehazing Model

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Abstract: In this paper we present an improved method for estimating the optical transmission t in hazy scenes in a given single input image. Firstly, a new formulation to estimate t is created by combining constant albedo and dark channel prior. Secondly, the watershed segmentation is introduced to divide the whole areas into some gray level consistent parts according to color distribution in the image so that user can better estimate the atmospheric light A , and also further avoid halo artifacts phenomenon. Finally, through this effective estimation to t and A , the scene visibility is largely increased and the haze-free scene contrasts can be better recovered. The experiment results demonstrate that our proposed method can provide comparable results to dark channel prior and obtain reliable estimation value t with the advantage of minimal halo artifacts and fewer unreal details.

Keywords: Dark-channel, dehaze, constant albedo, image enhancement, segmentation.

1. INTRODUCTION

Thus, haze removal has been more and more highly valued recently. However, it is restrictive to rely only on optical filtering because it can work well on clear days. The color of the output images is likely to be changed, which is a weakness of this approach. Range of radar target like one-dimensional projection [1] reflection characteristics of the target in the radar line of sight, reflect the fine structure of target vertical, offers more information for target detection, recognition and tracking. High resolution radar signal (such as linear frequency modulation pulse signal processing process is usually an echo signal coherent mixing and digital sampling, using the inverse discrete Fourier transform of pulse compression radar target, realizing the high resolution imaging. Although the discrete Fourier transform calculation speed is fast, but its essence by the resolution of radar transmitting signal bandwidth constraints. To obtain a higher resolution, the need to increase the bandwidth of the signal, thus increasing the amount of data storage.

At present there have been some features based on multi scattering center model to extract the data compression technology, such as Relax algorithm, multiple signal classification ([2] MUSIC, multiple signal classification [3]) algorithm, the matching pursuit (MP, matchingpursuit) [4]. The Relax algorithm is essentially a matching pursuit algorithm and the alteration product scale optimization method combining, does not have the super resolution [5]; MUSIC algorithm requires a more accurate estimation of the covariance matrix. At the same time, these methods inevitably model order problem, problem solving may also encounter the non-linear least squares [6].

If the model with information of target scattering characteristics, echo data using a sparse sampling of the implement

tation of high resolution reconstruction of range image, will be an effective way to solve the problem. The one-dimensional distance image as a time signal, imaging process is actually signal representation problem. From the classical Fu Liye analysis to wavelet developed in recent twenty years analysis, are to be analyzed signal in the orthogonal basis (or double orthogonal basis) expansion for signal analysis and synthesis, to achieve signal representation purposes, so as to obtain the natural characteristics of object [7-11].

This paper is based on the parametric diffraction model of radar target, discussed the sparse component analysis is applied to the high resolution range profile is effective way to sparse representation, proposes a super-resolution ability and sparse regularization function ability [12]. Using the high accuracy range profile simulation data, verified the rationality of selection criterion validity and regularization of the sparse representation of the function.

This paper introduces the traditional methods of image enhancement. For some traditional methods and puts forward some improvement. The experimental results also show that the improved method has no ideal effect to. Since the last century 90's layered image technology is applied to medical image since the image enhancement technology in medical image is more and more widely application of towel. Image post office is currently system has also been attention. The last part of this paper discussed the specific methods of endoscopic color image enhancement glimpse of a, and the use of the parallel computing method is optimized to experiment to accelerate.

2. IMAGE DEHAZING MODEL

2.1. Some Representative Dehazing Models

Each pixel of the color image is usually represented by 3 bytes, each byte corresponds to the RGB component of the brightness, and a pixel gray level image transformed by a

byte to represent, the little gray value greater brightness is bright [13];

$$I(x) = J(x)t(x) + A(1 - t(x)) \quad (1)$$

where $I(x)$ is the apparent luminance at pixel x , and $J(x)$ is the transmission of the map. A is called atmospheric light. This optical model is directly extended to each RGB component [14, 15].

The input value of gray level higher than the compressed into narrow output image in lighter gray level, the output is high contrast images:

$$S = T(r) = \frac{1}{1 + (m/r)^E} \quad (2)$$

According to the formula, Histogram equalization $S(x, x)$ on the input gray level executive changes the output gray level S [16].

$$s = T(r) = \int_0^r p_r(\omega) d\omega \quad (3)$$

In the formula (W) representation of the probability density function of the gray level in a given image, W is the 11 sub variable integral. You can get the probability density function of the output gray level is homogeneous [17, 18]:

where $J_c(y)$ is a color channel of $J(x)$ and $\Omega(x)$ is a local patch centered at x . Our observation says that except for the sky region, the intensity of J dark is low and tends to be zero, if $J(x)$ is a haze-free outdoor image. We call $J_{dark}(x)$ the dark channel of $J(x)$, and we call [19, 20]

Based on this observation, He assumes that $J_{dark}(x)$. By combining this assumption with equation (1), he proposes a new equation to estimate the transmission:

$$(I_c(y) - t(x)) / (I_c(y) - \min_c I_c(y)) = 1 - t(x) \quad (4)$$

$$t(x) = \frac{I_c(y) - \min_c I_c(y)}{I_c(y) - A} \quad (5)$$

$$I(x) = t(x)J(x) + A(1 - t(x)) \quad (6)$$

In terms of these normalized components, he projects the input image along and perpendicular to the atmospheric light:

$$I_A(x) = t(x)l'(x)h + (1 - t(x))A \quad (7)$$

$$I_R(x) = t(x)l'(x) \quad (8)$$

where $I_A(x)$ and $I_R(x)$ are components parallel and vertical to atmospheric light and generally hbe refined as:

$$h(x) = (A - I_A) / I_R \quad (8)$$

2.2. Estimating Transmission

Image registration in the mathematical formula (9) can be shown.

$$\lambda \cdot u \cdot \operatorname{div} \left(\frac{\nabla u}{|\nabla u|} \right) + H'(u) = 0 \quad (9)$$

Among them, I_1 and I_2 represent the two fusing image representation of the two-dimensional matrix, $I_1(x, y)$ and $I_2(x, y)$ represent the two images in $I_2(x, y)$ where δ is one-

dimensional gray value, gray level transformation, f represents a two-dimensional coordinate transformation.

The original image signal for embedding hypothesis representation, x_n representation of signal SNR is expressed was shown in formula (10):

$$\lambda \cdot \operatorname{div} \left(\frac{\nabla u}{|\nabla u|} \right) + \frac{H'(u)}{u} = 0 \quad (10)$$

Let it change for the bubble, if meet the formula full weight:

$$\int_R \frac{|\hat{\psi}(\omega)|^2}{\omega} d\omega < \infty \quad (11)$$

According to the formula (11) for dilation and translation of the basic wavelet, telescopic translation after a wavelet series $\Psi_{a,b}(t)$:

$$\Psi_{a,b}(t) = \frac{1}{\sqrt{|a|}} \psi \left(\frac{t-b}{a} \right) \quad a, b \in R, a \neq 0 \quad (12)$$

The definition of Daubechies series wavelet basis for:

$$p(y) = \sum_{k=0}^{N-1} C_k^{N-1+k} y^k \quad (13)$$

Where C is the binomial coefficient, so:

$$|m_0(w)|^2 = (\cos^2(\frac{w}{2}))^N p(\sin^2(\frac{w}{2})) \quad (14)$$

2.3. Halo Artifacts Removal with Segmentation

Fig. (1a) in the dotted and solid lines depict the absolute value form and two forms of one dimensional regularization function graph, two forms of visible modified remained the absolute value of the characteristic form, just near the origin become smooth and some. The function with P decreased more steep, in the optimization process more easily make the argument to the origin of compression. Fig. (1b) depicts the isoline map of two-dimensional regularization function, with the origin as a starting point in the direction of the ray, the value of the function is monotonically increasing. Linear formed in the graph represents the feasible set of linear $Y=FX$, minimum 7 regularization function in the linear feasible set (X), the optimal solution in a coordinate axis. Visible, the optimal solution of optimization problems containing as little as possible nonzero component, so regularization function is proposed in this paper has the ability of superresolution and sparse representation ability.

From Fig. (1a) can be seen, the more hours of P regularization function at the origin is sharpening, iterative process can accelerate the optimization solution, and the number of nonzero components of the vector will fall. However, P had a small regularization function will be very steep, can lead to numerical results are not robust [8].

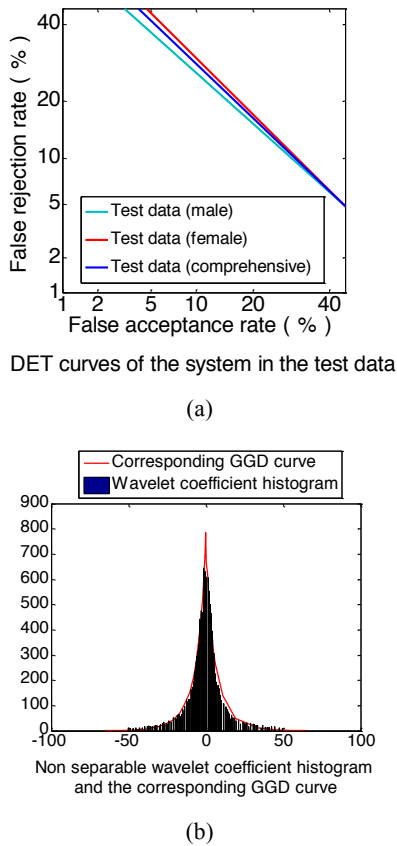


Fig. (1). The dotted and solid lines depict the absolute value.

2.4. Estimating the Atmospheric Light

Because the regular sparse component analysis of general function is a concave function of nonlinear, at the origin of differentiability is poor; and the sparse representation of the goal is to make the minimum coefficient of non null components, which will increase the difficulty of function optimization. Consider the complete decomposition of the regularized problem form, the process of nonlinear optimization search direction can be regarded as the projection direction of the negative gradient regularization function in the feasible set on. Intuitively, the gradient regularization function at the origin is close to zero, zero component solution vector will have more. The regularization process is the solution vector in smaller component compression is zero. Fig. (2) showed (a) The input image (b) Fattal's result (c) The revised transmission map (d) Segmentation with the scene (e) Our result with 0.95 (f) Our result with 0.9.

This paper studies the environment in the context of a fixed, face positions. Under normal circumstances, you can adjust the camera so that the current operating environment accounted for a central location in the image, but most of the time the image is only the operator, and therefore is primarily a single person's face detection overcast (Fig. 3).

According to the echo number respectively calculate the one-dimensional distance of two times and four times of super resolution super resolution image, in which $p=0.001$, the regularization parameter are respectively $K=1.0$ and $K=3.0$, step $C=1$. As the space plan, Fig. (3) gives only four times to reconstruct the super resolution range profile. The

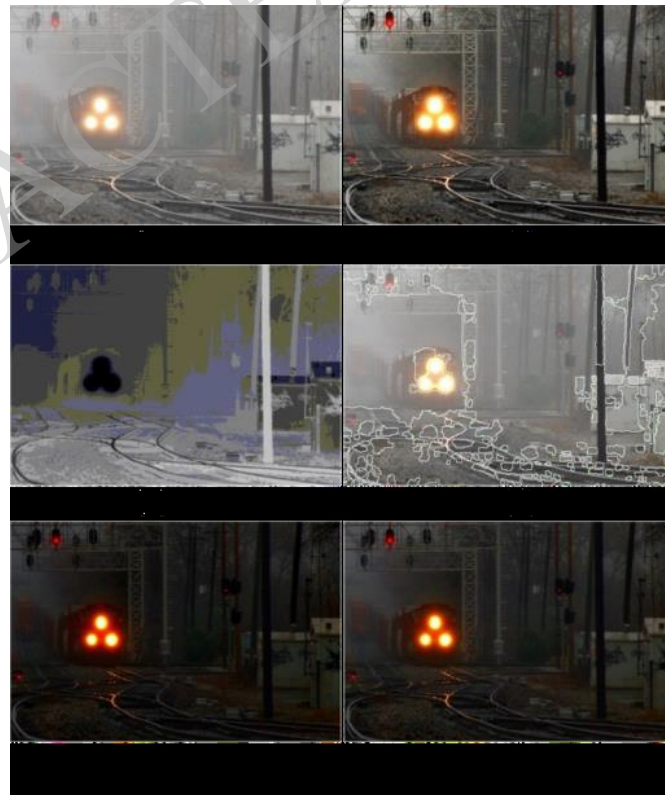


Fig. (2). (a) The input image (b) Fattal's result (c) The revised transmission map (d) Segmentation with the scene (e) Our result with 0.95 (f) Our result with 0.9.

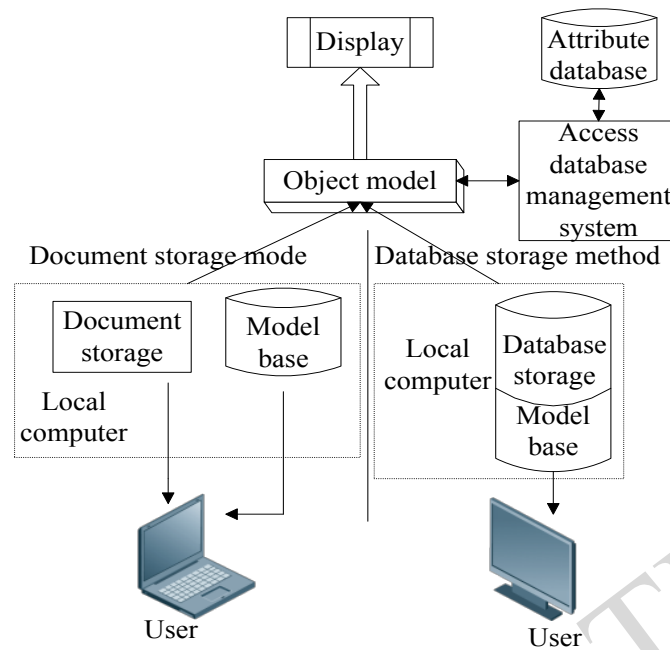


Fig. (3). Establishment of skin color clustering model.



Fig. (4). Comparison with Tan's work [3]. Left: input image, middle: Tan's result, right: our result.

reconstruction results of scattering centers in the type parameter of the $A=0$ amplitude occupies the absolute dominant position, the reason is that the electromagnetic computing software bandwidth limitations and the calculation does not include geometrical theory of diffraction field.

3. RESULTS AND SIMULATION

3.1. Build Computational Models

Still with the echo data in section second, take superresolution multiple $l=4$. We select the different P values and the corresponding regularization parameter K to examine the signal reconstruction results. In the $\pi[0.001,0.1]$ and $p=1.0$, the regularization parameter $K=3.0$, technical analysis of

echo data processing using sparse component section second. At the same time, using the matching pursuit method for distance image reconstruction, as shown in Figs. (4 and 5).

Due to the sensitive degree of the human eye to color changes are the sensitive degree of alignment light intensity changes play a lot higher, so the use of K brightness and brightness is located in matching engineering to select suitable m chroma of color reproduction. After the formula for conversion, and then use the formula underlying all pixels of image and standard image respectively in 2 dimensional Euclidean distance calculations so that you can get a maximum Euclidean distance and the minimum Euclidean distance. The maximum distance of the obtained pixel and minimum distance between pixels S can put the color standard value of the image chroma in conversion to standard image.



Fig. (5). (a) The input image; (b) Segmentation result of the scene (c) Segmentation result without the scene (d) The result (e) Fattal's result (f) Test result.

3.2. Experimental Results and Analysis

If you use the most intuitive way to calculate the Euclidean distance, which need huge storage space. That is, to play in each work item to please an image size of the space, for small image can be done, but for larger image, before the GPU foot cannot meet. In order to ensure the universality and can fast calculation program, this experiment selection method using sacrificial inch asked in exchange for space. The need for another 6 data space in each work item towel, maximum entropy, minimum entropy stored separately and their corresponding coordinate position (coordinates of each requires two memory space). Fig. (6): (a) The input image (b) *Fattal's* result (c) *Tan's* result (d) *Koph et al.'s* result (e) Our result with $0.95 \omega =$ (f) The revised transmission map according to the description of the Shannon entropy, Chang maximum image enough Pei strong image contains the maximum amount of information, that is, set contrast strong image. On the experimental observations, found that pick for application two square degree although image started strong and. Spectral image with the largest cannon in the organization's table and characteristics also have very big to strong; secondly, spectral again if no maximum wavelength used 500nm

image reconstruction of the image color. Experiments using the light maximum Connaught enough entropy selection based on image.

In the method of color reproduction, make a Q neighborhood statistics in topological empty Tongchuan method for color reproduction. Color reproduction completed the standard image and N image of the standard color for color ask. In order to make the method is simple, usually from a palette of RGB color coloring. In the methods of this chapter, methods of using neighborhood statistics from the standard image by brightness and texture information of the image conversion, ask all chroma to grayscale spectral image, and only conversion chrominance times message to standard image.

CONCLUSION

Sparse component analysis has important theory and application value in the signal analysis and signal super resolution reconstruction, natural features can effectively acquire the signal in the, and can be applied to the feature extraction and automatic target recognition and other fields. High resolution image sparse representation of distance, can be



Fig. (6). (a) The input image (b) *Fattal's* result (c) *Tan's* result (d) *Koph et al.'s* result (e) Our result with $0.95 w =$ (f) The revised transmission map

reduced in sampling system, reduce the storage capacity. At the same time, it also can be used as an effective feature of the target, for the identification of follow-up treatment. The proposed regularization function selection criteria and corresponding regularization function can also be applied to sparse 2-D radar imaging said, according to the type of the scattering centers of the target scattering center can obtain higher resolution distribution. Of course, with super resolution method has higher complexity, problem solving will cost much more time and resources. Sparse component analysis technology is having a higher resolution, but the amount of calculation than the FFT algorithm significantly increased, limit their application in radar signal processing system for real-time in need, so research on the calculation method of high efficiency.

CONFLICT OF INTEREST

The authors confirm that this article content has no conflicts of interest.

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